

### Atmospheric and Surface Property Retrievals from IASI and NAST-I

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# **Presentation Outline**



- Introduction
- PCRTM forward model and retrieval algorithm
- Results from IASI and NAST-I
- Conclusions

# Introduction



1305 x 3 x 3

8632 x 1 x 1

### • Modern hyperspectral sounders have thousands of channels

- AIRS (Atmospheric Infrared Sounder): 2378 x 1 x1
- CrIS (Cross Track Infrared Sounder):
- NAST-I (NPOESS Airborne Sounder Testbed):
- IASI (Infrared Atmospheric Sounding Interferometer)
  8461 x 2 x 2
- GIFTS (Geostationary Imaging Fourier Transform Spectrometer): 1827 x 128 x 128

#### • Channel radiances are difficult to calculate

- Double integral non-linear equation

$$\begin{split} R_{\nu} &= \int_{\Delta\nu} \{ \varepsilon_{\nu} B_{\nu}(T_{s}) t_{s,\nu} + \int_{p_{s}}^{0} B_{\nu}(T(p)) \frac{\partial t_{\nu}(p,\theta_{u})}{\partial p} dp \\ &+ (1 - \varepsilon_{\nu}) t_{s,\nu} \int_{0}^{p} B_{\nu}(T(p)) \frac{\partial t_{\nu}^{*}(p,\theta_{d})}{\partial p} dp + \rho_{\nu} t_{s,\nu} t_{\nu}(p_{s},\theta_{sun}) F_{0,\nu} \cos \theta_{sun} \} \phi(\nu - \nu') d\nu' \\ &= \int_{\Delta\nu} \{ \varepsilon_{\nu s} t_{\nu,N_{bot}} B_{\nu,s} + \sum_{i=N_{bot}}^{N_{top}} (t_{\nu,i-1} - t_{\nu,i}) B_{\nu,i} + (1 - \varepsilon_{\nu s}) t_{\nu,N_{bot}} \sum_{i=N_{top}}^{N_{bot}} (t_{\nu,i}^{*} - t_{\nu,i-1}^{*}) B_{\nu,i} \\ &+ \rho_{s} t_{\nu,N_{bot}} t_{sun}(p_{s},\theta_{sun}) F_{0,\nu} \cos \theta_{sun} \} \phi(\nu - \nu') d\nu' \end{split}$$

#### • Key to utilizing the high information content of hyperspectral data

- Fast and accurate radiative transfer model
  - Explore channel-to-channel correlations
- Efficient and stable retrieval algorithm
  - Use as many channels as possible to beat down the instrument noise

### predicts PC scores (Y) instead of channel radiances (R)

PC scores (super channels) are linearly related to channel radiances

Principal Component-based Radiative Transfer Model (PCRTM)

$$\vec{Y} = A \times \vec{R}^{mono}$$

• The relationship is derived from the properties of eigenvectors and instrument line shape functions:

$$\vec{Y} = U^T imes \vec{R}^{char}$$

$$R_i^{chan} = \frac{\sum_{k=1}^N \phi_k R_k^{mono}}{\sum_{k=1}^N \phi_k}$$

- Jacobian is provided in EOF space directly
- Very accurate relative to LBL
  - Accuracy of the model can be adjusted
- Cloud contributions included
- Channel radiances (or transmittances ) can be obtained easily

$$ec{R}^{chan} = U imes ec{Y} = \sum_{i=1}^{N_{EOF}} y_i ec{U}_i + ec{arepsilon}$$

• Liu et al Applied Optics 2006

# **Description of PCRTM**



# **Results of Applying PCRTM to IASI**







- An Example of the IASI spectrum and the difference between the LBL calculated radiance and the PCRTM calculated radiance
- Errors less than 0.05 K

#### **PCRTM** accuracy:

- Top: RMS error
- Middle: Bias error
- IASI instrument noise
- Very good relative to LBL
- Much smaller error relative instrument noise

# **Comparison with NAST-I observations**



- NAST-I spectrum take over Potenza Italy on September 9th, 2004
- Emissivity fix to 0.98 (not the truth)
- T, H<sub>2</sub>O taken from LIDAR measurements
- O<sub>3</sub> fixed to US standard ATM
- PCRTM and LBLRTM calculated radiances agree with each other (< 0.07 K)
- main sources of error between the NAST-I observed and PCRTM calculated radiances
  - Spectroscopy
  - Uncertainty in the "true atmospheric state"



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# Flow diagram of the PCRTM retrieval algorithm





 $X_{n+1} - X_a = (K^T S_y^{-1} K + \lambda I + S_a^{-1})^{-1} K^T S_y^{-1} [(y_n - Y_m) + K(X_n - X_a)]$ 

- All parameters retrieved simultaneously
  - No need to estimate errors of non-retrieved parameters
- Very robust
  - Can start from either climatology or regression first guesses
- Single FOV retrieval
  - High spatial resolution
  - Cloud parameters retrieved explicitly
  - Multiple scattering effect included
- Provide error covariance matrix of state vector without extra calculations
  - Provides info needed by 3D/4Dvar
  - Error correlations included
  - Compressed state vector and associated error covariance matrix
- Both radiance and state vectors are in EOF domain
  - Small matrix and vector dimensions
  - Simply minimizing cost function
  - No ad hoc tuning parameters

# Retrieved Surface Skin Temperature and Cloud Properties Near Anglet France (Nov. 4, 2007)





### 3-D Atmospheric Temperature, H<sub>2</sub>O, O<sub>3</sub>, and CO Structure over Anglet France

![](_page_8_Picture_1.jpeg)

- A movie showing IASI T, H<sub>2</sub>O, O<sub>3</sub>, and CO cross-sections on November 4, 2007
  - T and H<sub>2</sub>O as a function of altitude
  - T and  $H_2^{-}O$  along satellite track
  - T and  $H_2O$  x-track
  - CO and  $O_3$  as a function of altitude

![](_page_8_Figure_7.jpeg)

### 3-D Atmospheric Temperature, H<sub>2</sub>O, O<sub>3</sub>, and CO Structure over Anglet France

![](_page_9_Picture_1.jpeg)

- Another movie showing IASI T, H<sub>2</sub>O, O<sub>3</sub>, and CO cross-sections on November 4, 2007
  - T and  $H_2O$  as a function of altitude
  - T and  $H_2O$  along satellite track
  - T and  $H_2O$  x-track
  - CO and  $\overline{O}_3$  as a function of altitude

![](_page_9_Figure_7.jpeg)

## Comparison of T and RH Between PCRTM Retrieval and Radiosonde Near Anglet France (Nov. 4, 2007)

![](_page_10_Picture_1.jpeg)

![](_page_10_Figure_2.jpeg)

# Retrieved Cloud Parameters and Surface Skin Temperature (April 19, 2007, JAIVEX)

![](_page_11_Picture_1.jpeg)

![](_page_11_Figure_2.jpeg)

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# **Results from JAIVEX Campaign (April 19, 2007)**

![](_page_12_Picture_1.jpeg)

- Fine water vapor structures captured by the retrieval system
- NAST-I under flew over the CART ARM site
- A very cloudy sky condition

Lon. (deg.)

![](_page_12_Figure_5.jpeg)

Lat. (deg.)

![](_page_12_Figure_6.jpeg)

- Cross-section of retrieved ozone at ~ 16 km
- Plot is deviation from the mean
- High latitudes have higher ozone amounts than low latitudes
- Fine horizontal structure captured
- Can be correlated with T and H<sub>2</sub>O

# Comparison of IASI and NAST-I retrieved profiles with radiosondes

- Retrieved atmospheric
  Temperature and moisture
  profiles from IASI and NAST-I
- All parameters retrieved
  - T, H<sub>2</sub>O, O<sub>3</sub>,CO
  - Surface emissivty
  - Surface skin temperature
  - Cloud optical depth
  - Cloud height
  - Cloud particle size
- Good agreement between
  IASI and NAST-I
- Good agreement with radiosonde

![](_page_13_Figure_11.jpeg)

# Ts and cloud properties for April 29, 2007

![](_page_14_Picture_1.jpeg)

- Retrieved surface skin temperature and cloud properties from IASI
- NAST-I under flew over the gulf of Mexico
- Relatively clear day
- Only drop sondes available from the UK aircraft

![](_page_14_Figure_6.jpeg)

### **Results from JAIVEX Campaign (April 29, 2007)**

![](_page_15_Picture_1.jpeg)

- A movie showing 3-D atmospheric structures of T and H<sub>2</sub>O
- NAST-I under flew over the gulf of Mexico
- Notice the fine moisture circulation pattern

![](_page_15_Figure_5.jpeg)

# Comparison of retrieved T & RH profiles with dropsondes for April 29, 2007

![](_page_16_Picture_1.jpeg)

4

50

4

50

- Moisture profiles highly variable
- Changes on the scale of a few km
- PCRTM IASI retrieval can capture various H<sub>2</sub>O layers
- Agreement should improve if careful footprint matching is done

![](_page_16_Figure_6.jpeg)

![](_page_16_Figure_7.jpeg)

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# **Spectral residuals and CO retrievals**

300

![](_page_17_Picture_1.jpeg)

- Red curve and blue curve in the top panel are IASI observed spectrum and PCRTM modeled spectrum
- Red curve in the bottom panel is the rms error
- Blue curve in the bottom panel is the IASI instrument noise converted to the brightness temperature unit (K) using the scene temperature shown in the upper panel
- 280 spectrum 240 F AST 180 500 wavenumber (cm<sup>-1</sup>) 8 RMS Error 4 wavenumber (cm<sup>-1</sup>) 280 spectrum 240 AST wavenumber 8 RMS Error 6

wavenumber (cm<sup>-1</sup>)

 Notice that the feature near 2020-2250 cm<sup>-1</sup> are removed when CO profile is explicitly retrieved in the inversion algorithm

## **Comparison of IASI retrieved profiles with ECMWF**

![](_page_18_Picture_1.jpeg)

![](_page_18_Figure_2.jpeg)

![](_page_18_Figure_3.jpeg)

# Examples PCRTM Retrieved land and ocean emissivities

![](_page_19_Picture_1.jpeg)

![](_page_19_Figure_2.jpeg)

![](_page_19_Figure_3.jpeg)

- Soil (or quartz, or ?) + vegetation
  - → produce ARM CART site observed emissivity
- Retrieval is not sensitive to emissivity at frequencies where the IASI does not see the earth's surfaces
  - ightarrow 645-750 cm<sup>-1</sup>, 1400-2000 cm<sup>-1</sup>

![](_page_19_Figure_8.jpeg)

- NAST-I retrieved sea Emissivity
  - $\rightarrow$  On Sept. 9, 2004 near Italy
  - →Wind speed and scan angle dependencies included
- Retrieval is not sensitive to emissivity at frequencies where the IASI does not see the earth's surfaces
  - ightarrow 645-750 cm<sup>-1</sup>, 1400-2000 cm<sup>-1</sup>

# Conclusions

![](_page_20_Picture_1.jpeg)

- PCRTM is a physical based fast radiative model
  - Accurate relative to LBL
  - Very fast in speed
  - Cloud effect modeled (including multiple scattering)
  - Provides forward model and Jacobians in both spectral and EOF domain
- A Single FOV physical retrieval methodology has been developed
  - Small dimensions for both observation and state vectors
  - Retrieves all state vector simultaneously
  - Cloud parameters retrieved explicitly
    - No need for cloud clearing
    - High horizontal resolution relative to cloud clearing method
  - Converges quickly even from climatology first guess
  - Provide error covariance of retrieved parameters
- PCRTM retrieval method has been applied to IASI and NAST-I
  - Capturing high vertical and horizontal atmospheric structure
  - Coherent spatial field retrieved for all parameters
  - Compare well with radiosondes and ECMWF profiles
- Excellent IASI data
  - Provide atmospheric and surface properties
    - T, H<sub>2</sub>O, O<sub>3</sub>, CO, cloud O, cloud height and cloud effective size
    - Surface skin temperature and surface emissivities
  - Consistent with NAST-I retrievals
  - Agree well with radiosondes and drops sondes
- Application of PCRTM retrieval algorithm
  - Incorporate into 3D/4DVAR NWP system
  - Assimilate the PCRTM retrieved parameters in NWP system (error cov provided)