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# IASI QUARTERLY PERFORMANCE REPORT FROM 2009/12/01 TO 2010/02/28

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BY IASI TEC (TECHNICAL EXPERTISE CENTER)

FOR IASI FM2 METOP A





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## LIST OF ACRONYMS

[ TBC ]	To be confirmed	
[ TBD ]	To be defined	
APO	Other Parameters OPS	
AR	Anomaly Report	
BRD	BoaRD configuration	
CGS	Core Ground Segment at EUMETSAT	
CNES	Centre National d'Etudes Spatiales	
DA	Applicable document	
DPS	Data Processing Subsystem	
EPS	EUMETSAT Polar System	
EUMETSAT	European organisation for exploitation of METeorological SATellites	
FM2 / FM3	Flight Model n°2 or 3	
IASI	Infrared Atmospheric Sounding Interferometer	
IIS	IIS Integrated Imaging Subsystem	
METOP METeorological OPerational satellite		
OPS	Operational Software	
PDU	Power Distribution Unit	
PL SOL	Payload switch off-line (It's a spacecraft anomaly external to IASI but still resulting in a switch off of the instrument.	
PTSI	Parameter Table Status Identifier	
RD	Reference document	
SEU	Single Event Upset	
TEC	IASI Technical Centre of Expertise (located in CNES, Toulouse)	
VDS	Verification Data Selection	





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## 1 <u>INTRODUCTION</u>

The IASI TEC is based at CNES Toulouse and is responsible for the monitoring of the IASI system performances, covering both instrument and level 1 processing sub-systems.

This document describes the activities and results obtained at the IASI TEC for instrument FM2 on METOP-A during the following period:

Start Time: 2009/12/01 Orbit: 16171
 End Time: 2010/02/28 Orbit: 17450

• Duration:3 months

Note that IASI end the Calibration / Validation (commissioning) phase on July 2007.

## 2 RELATED DOCUMENTS

## 2.1 APPLICABLE DOCUMENTS

N°	Reference	Titre				
DA.1	IA-SP-0000-3242-CNE	Spécification de suivi de la performance en vol de IASI sur METOP-A				

#### 2.2 REFERENCE DOCUMENTS

N°	Reference	Titre			
RD.1	EUM/OPS/-EPS/TEN/08/206710	IASI annual in-flight review 1st February 2007 - 31st August 2008			
RD.2	RD.2 EUM/OPS-EPS/REP/09/0223 IASI annual in-flight performance report 2009				





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#### 3 SIGNIFICANT EVENTS

The following tables present a timeline of the various requests sent by TEC and the external IASI activities.

Those events are typically the configurations change, programming requests, software update, but also any external operation or activity such as mission interruption, manoeuvre, dissemination problem, ...)

#### 3.1 EXTERNAL CALIBRATION

Table 1 shows the External Calibration within the time period reported here. Note that the VDS files that come with each request are not described here.

Execution	TEC ref.(1)	Description	Activities
19/12/2009 from 5h15 to 9h11 orb. 16430 to 16432	n 5h15 to 9h11 RM-29 Targets: Earth 15,		For routine monitoring (IIS and IASI NeDT, scan mirror reflectivity, ghost,)
from 03/01/10 22h46 to 04/01/10 20h46 orb. 16654 to 16667	RL-07	Moon avoidance MPF <sup>(2)</sup> Targets: 1 <sup>st</sup> Deep Space	Monitoring of moon intrusion in CS1 FOV
17/01/2010 from 5h15 to 9h11 orb. 16842 to 16844	RM-30	Monthly_MPF <sup>(2)</sup> Targets: Earth 15, Blackbody, 2 <sup>nd</sup> Deep Space, Mirror Backside	For routine monitoring (IIS and IASI NeDT, scan mirror reflectivity, ghost,)
15/02/2010 from 5h15 to 9h11 orb. 17254 to 17256	rom 5h15 to 9h11 RM-31 Targets: Earth 15, Blackbody,		For routine monitoring (IIS and IASI NeDT, scan mirror reflectivity, ghost,)

Table 1: External Calibration TEC Requests

- · a TEC request or
- a "MPF" uploaded directly by EUMETSAT in full accordance with TEC. The reference "Monthly\_MPF" is based on the March 2008 TEC External Calibration request. The MPF for moon avoidance is based on the December 2008 TEC External Calibration request: "ICAL\_OCF\_xx\_M02\_20081216060000Z\_20090616060000Z\_20081209100934Z\_IAST\_EXTCALIBRA.dts"

#### 3.2 ON BOARD CONFIGURATION

Table 2 presents the on-board processing configuration updates that had been made within the time period reported here:

PTSI	IASI on board parameter files	Delivery by TEC	activated on	TEC ref.	affected parameters of a DPS TOP configuration update

Table 2: DPS and MAS configuration TEC Requests

For information, Table 3 shows the delivery applicable at the beginning of the period:

PTS	I IASI on board parameter files	Delivery by TEC	activated on	TEC ref.	affected parameters of a DPS TOP configuration update
12 2.0	IDPS_OBP_xx_M02_ 20090216161739Z_20090816161739Z_ 20090216161854Z_IAST_ DPSPARAMOD.tar	16/02/2009 16h	24/02/2009 13h53 orbit 12202	R_36	Update of reduced spectra 58: IRscSrd 59: IRshSrd 64: PTSI (0x0200 000C)

Table 3: DPS and MAS previous configuration

The associated ground configuration table (BRD file), necessary to handle coherent configuration at system level, is presented in the next section. These associated configuration table are necessary for L1 processing.

<sup>(1)</sup> TEC convention: R for Routine, M for Monthly and L for moon avoidance, followed by a chronological number

<sup>(2)</sup> An external calibration could be the result of:





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#### 3.3 GROUND CONFIGURATIONS UPDATES FOR LEVEL 1 PROCESSING

Table 4 presents the on-ground processing configuration updates that had been made within the time period reported here:

IDef	IASI L1 auxiliary files	Delivery by TEC	Delivery to GS1	Comments on upload	Comments on content

Table 4: IASI L1 Auxiliary File Configuration on the Operational EPS Ground Segment

For information, Table 5 shows the delivery applicable at the beginning of the period:

IDef	IASI L1 auxiliary files	Delivery by TEC	Delivery to GS1	Comments on upload	Comments on content
37	IASI_BRD_xx_M02_20090415060000Z _xxxxxxxxxxxxZ_20090414125404Z _IAST_0000000012 IASI_GRD_xx_M02_20090415060000Z	14/04/2009 at 13h Z		SMA group corresponding to scan mirror reflectivity	BRD: On ground relation with new GRD GRD: New SMA group
7	xxxxxxxxxxxxxZ_20090414125412Z_IA   ST_0000000017   IASI_ODB_xx_M02_20070705200000Z   xxxxxxxxxxxxxZ_20070705153529Z   IAST_0000000007	27/02/2008 at 16h Z	24/02/2009 13h57 Z orbit 12202		

Table 5: IASI L1 auxiliary file previous configuration

#### 3.4 DATA BASES UPDATE FOR THE USERS

The Noise Covariance Matrix (NCM) and Spectral data base (SDB) are specific data bases for the users. They are updated according to the main ground level 1 evolutions.

Table 6 presents the updates of the NCM and SDB that had been made within the time period reported here:

IDef	Users Data-Base	Delivery by TEC	TEC ref.	Comments
3	IASI_NCM_xx_M02_20091217060000Z _20091217060000Z_20091216123652Z_ IAST_SPECTRESPO	16/12/2009		Noise Covariance Matrix after decontamination; Covariance matrix from L0 noise on BB (External Calibration of 2009/10/22)

Table 6: IASI Data Bases for the users

For information, Table 7 shows the delivery applicable at the beginning of the period:

IDef	Users Data-Base	Delivery by TEC	TEC ref.	Comments	
2	IASI_NCM_xx_M02_20080428120000Z _20080428120000Z_20080428082548Z_ IAST_SPECTRESPO 23/04/2008 R_COV_2		R_COV_2	Noise Covariance Matrix after decontamination; Covariance matrix from L0 noise on BB (External Calibration of 2007/03/31)	
7	IASI_SDB_xx_M02_20070705200000Z_ 20070705200000Z_20070705161316Z_ IAST_IASISPECDB	05/07/2007	CVC_32	User database associated to ODB IDefSDB 7	

Table 7: previous IASI Data Bases





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#### 3.5 ON GROUND HW/SW EVOLUTION

Table 8 presents the updates of PPF L1 software within the time period reported here:

IASI L1 PPF software version	Delivery by TEC	Date introduced on GS1	Comments

Table 8: IASI L1 PPF Configuration on the Operational EPS Ground Segment

For information, Table 9 shows the software version applicable at the beginning of the period:

IASI L1 PPF software version	Delivery by TEC	Date introduced on GS1	Comments
4.0.3	18/08/2008	29/09/2008 for sensing time 06:35 <sup>UTC</sup> Orbit 10095	

Table 9: Previous IASI L1 PPF

#### 3.6 DECONTAMINATION

Table 10 presents decontaminations that have been made or requested within the time period reported here:

Last due date	Date of decontamination	Description		

Table 10: Decontamination TEC Requests

For information, Table 11 shows the previous decontamination:

Last due date	Date of decontamination	Description
July 2008	20/03/2008	

Table 11: Previous decontamination

#### 3.7 INSTRUMENT

#### 3.7.1 External events

This category is for those activities/events that are external to IASI but still have an impact. It is broken down into classes of *PL-SOL* and *OOP* manoeuvre.

#### 3.7.1.1 Manoeuvres

Date	Type(*)	Description	IP flag	OoP mission Outage
10/12/2009	IP	IASI in Normal Operation	No for orbit 16308	

Table 12: Overview of METOP manoeuvres in the reporting period

<sup>(\*):</sup> IP for In-Plane manoeuvres (IASI stays in NOp) and OoP for Out of plane manoeuvres (IASI is put in Heater 2)





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#### 3.7.1.2 PL-SOL

Table 13 presents the PL-SOL events that have occurred within the time period reported here:

Dates	Orbits	Description

Table 13: PL-SOL

## 3.7.2 Operation leading to mission outage

This chapter present the intervention on IASI needing routine interruption that have occurred within the time period reported here.

Dates	Orbits	type	IASI mode	Description

Table 14: Scheduled interruptions

## 3.7.3 Anomaly leading to mission outage

Table 15 and Table 16 present the major and minor anomalies internal to IASI that have occurred within the time period reported here.

Note that, in this section minor anomalies are all identified and without any impact on the mission, and major anomalies only affect IASI instrument, and no other sub-systems of the spacecraft.

Dates	Orbits	Anomaly type (*)	IASI mode	Description

Table 15: Major anomalies

## (\*): SEU (LAS, CCM or DPS) anomalies or SET anomalies

Day	Orbits	error n°	Severity	Anomaly type	LN	SN	Description
2009/12/10 01:49:26	16300	13	2В	CCM CSQ	16080	07	see in TM but not in table ELT (saturated)
2010/02/20 13:15:24	17330			CCM CSQ		32	see in TM but not in table ELT (saturated)

Table 16: Minor anomalies





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#### PERFORMANCE MONITORING

#### 4.1 PERFORMANCE MONITORING

In order to insure that the IASI system is permanently running in good conditions, the CNES (IASI TEC) and EUMETSAT (CGS) are monitoring each orbit, both at line, PDU and DUMP levels.

The on-board and ground processing performance algorithms issue more than one hundred quality indicators, called flags and simple parameters. Those are alarms for any bad functioning or local performance degradation.

According to the results, the TEC is also in charge of delivering new on-board or ground parameters to EUMETSAT when it is necessary. EUMETSAT is then in charge of uploading them on-board or as an input of the level 1 processing chain. During the whole instrument life, these parameter adjustments are necessary in order to take into account instrument evolution in the processing and finally to maintain a good data quality.

The Table 17 is the colour code used for the status report.

Status Colour	Meaning
GREEN	≥ 95
YELLOW	< 95
RED	Production interrupted
BLANK	No Status Reported

Table 17: Functional status legend





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## 4.2 PERFORMANCE SYNOPSIS

Table 18 provides a synthetic view of all the indicators evaluated for L0/L1 data and their current status.

Section	Component	Description	Status	Comments
4.3	LO	Level-0 Data Quality  Overall quality  Main flag and quality indicator parameters  Spikes monitoring  ZPD monitoring  Overflows/Underflows monitoring  Reduced Spectra monitoring  Second level flag and quality indicators	GREEN	On-board processing
4.4	L1	<ul> <li>Level-1 Data Quality</li> <li>Overall</li> <li>Main flag and quality indicator parameters</li> <li>Second level flag and quality indicators</li> </ul>	GREEN	On ground processing
4.5	L1	Sounder radiometric performances  Radiometric noise Radiometric calibration Optical transmission Interferometric contrast Detection chain	GREEN	
4.6	L1	Sounder spectral performances  Dimensional stability  Acquisition chain delay  Ghost evolution  Instrument parameters	GREEN	
4.7	L1	Geometric performances  Sounder/IIS co-registration  IIS/AVHRR co registration  PDD SCAN, SQ1 flag, SQ2 flag	GREEN	
4.8	L1	<ul> <li>IIS radiometric performances</li> <li>IIS radiometric noise monitoring</li> <li>IIS radiometric calibration monitoring</li> </ul>	GREEN	

Table 18: IASI product components functional status





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## 4.3 LEVEL 0 DATA QUALITY (L0)

## 4.3.1 Overall quality

The IASI L0 data quality (orbit average) through IASI engineering products is shown in Figure 1.

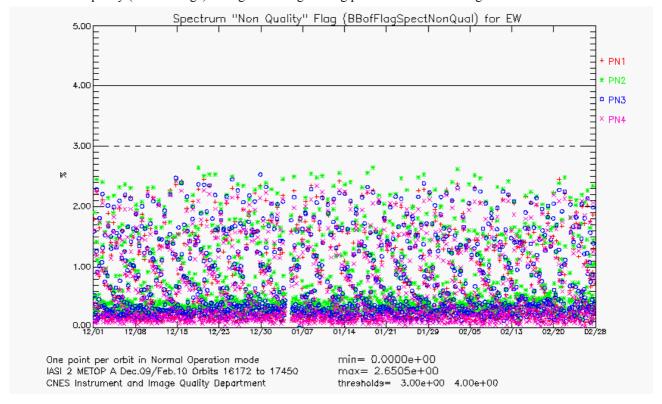


Figure 1: IASI L0 data quality orbit average (per pixel and CCD)

The IASI L0 quality and on-board processing are nominal.





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## 4.3.2 Main flag and quality indicator parameters

The main contributors to the rejected spectra by on-board processing are: the spikes (proton interaction on detectors), failure of NZPD algorithm determination and over/underflows (measured data exceeding on-board coding tables capacity). There are analysed in details hereafter.

#### 4.3.2.1 Spikes monitoring

Spikes occur when a proton hit a detector. This very high energetic particle disrupts the measure of the interferogram and then corrupts the spectrum.

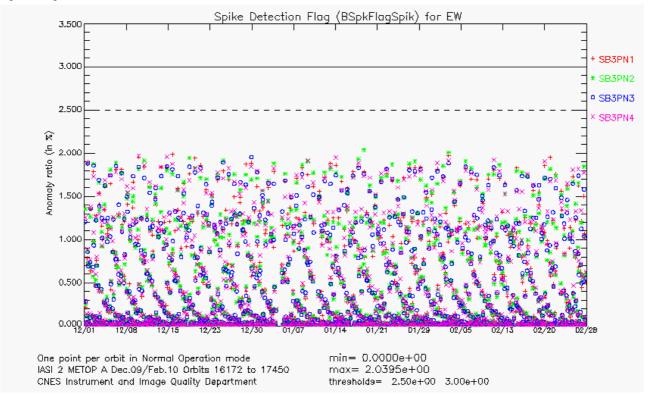


Figure 2: Temporal evolution of spikes anomaly ratio in % for all pixels (orbit average)

Spike anomaly ratio is nominal for the reported period.





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#### 4.3.2.2 ZPD monitoring

The ZPD ("Zero Path Difference") is the position of the central fringe of the interferogram. The NZPD is the number of the sample detected as the ZPD. On IASI, it is determined by a software. This is a special feature of IASI in comparison to other instruments for which NZPD determination is done by hardware.

NZPD variations are governed by two phenomenons:

- 1. ASE fluctuations which have the same effect on each pixel and can produce NZPD variation of 30-40 samples over month. This is the first order phenomena.
- 2. Mechanical deformation of the interferometer or evolution of detection chain delays. These phenomenons affect the 4 pixels in different way. However this phenomenon has a second order effect in comparison to the first one.

We monitor both NZPD determination quality flag and interpixel homogeneity. We expect a stability.

BZPDFlagNZPDNonQualEW: Temporal evolution of NZPD determination quality flag for earth view

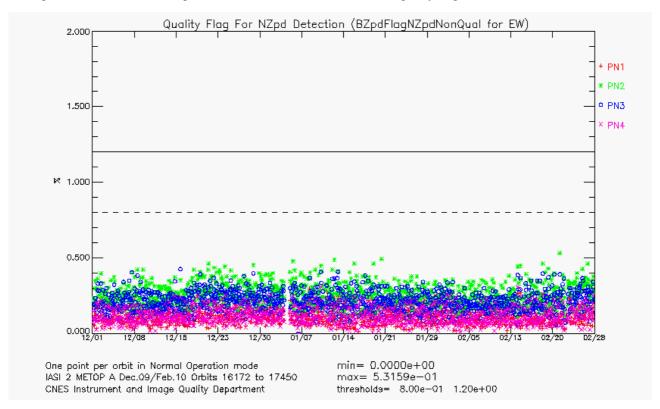


Figure 3: Temporal evolution of NZPD determination anomaly ratio in % for all pixels (orbit average)

NZPD determination anomaly ratio is nominal for the reported period.

#### NZPD inter-pixel homogeneity monitoring

This monitoring is necessary in order to follow potential deformation of the interferometer or evolution of detection chain delay.

It is performed on a regular basis. The NZPD inter-pixel homogeneity is nominal over the reported period.

Consequently, these parameters are perfectively stable and in-line with the specification. Graphs will be provided only for REVEX.





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#### 4.3.2.3 Overflows / Underflows monitoring

The total number of bits available for a spectrum to be transmitted to the ground is limited. For that reason, we have defined coding tables to encode each measured spectrum. These tables have been design by using "extreme spectrum" corresponding to known drastic atmospheric conditions. The coding step is also set to not introduce additional noise into the spectrum. However for very extreme atmospheric conditions (sunglint in B3, very high stratospheric temperature...) a measure can exceed on-board coding tables' capacity and causes an over/underflow.

We monitor over/underflows and we expect a stability. As long as they remain to low levels we do not change the coding table. Note that changing the coding tables is tricky: when you want to increase the encoding capacity of a given spectral band, you have two solutions. First you can increase the coding step without changing the number of bits. This leads to an increase of the noise level in the spectrum. The second solution consists in keeping the coding step constant and increasing the number of bits available for a particular band. Of course the total amount of bits available for the entire spectrum is limited and constant. So you will have taken them away from other spectral bands and consequently decrease encoding capacity of these corresponding bands.

Time series of Overflows and Underflows (orbit average) are shown in following figure for all pixels.

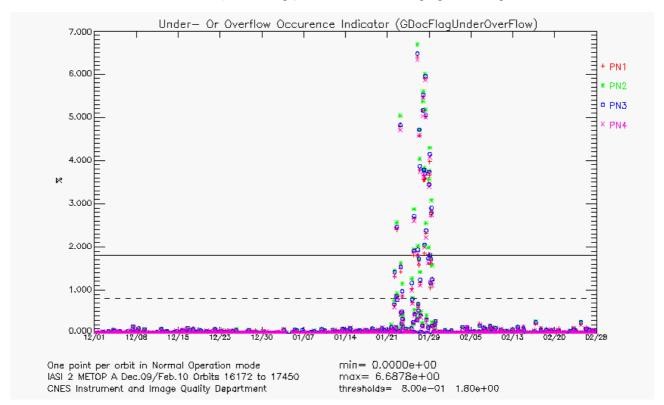


Figure 4: IASI L0 over/under-flows orbit average of all pixels

Over/underflows ratio is nominal for the reported period.

Note: the peak observed on the figure is due to high stratospheric temperature. This phenomenon, once a year, is related to the polar vortex collapse of the winter hemisphere. The consequence for IASI system is that the on-board coding tables are not able to encode this type of exceptional event around 2350-2400 cm<sup>-1</sup> (CO<sub>2</sub> band).





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#### 4.3.2.4 Reduced Spectra monitoring

On-board Reduced Spectra is one of the most important monitoring. It ensures that on-board spectra still have a good radiometric calibration when on-board configuration reduced spectra are reloaded. This is the case, for instance, after an instrument mode change.

Reduced spectra are slightly evolving with respect to potential deformation of the interferometer (optical bench).

In order to prevent a large difference between current and on-board configuration reduced spectra, we monitor the evolution of ZPD determination quality index for calibration views (BZpdNzpdQualIndexBB and CS) obtained by DPS processing by simulating a perpetual mode change. Results of this monitoring are given hereafter.

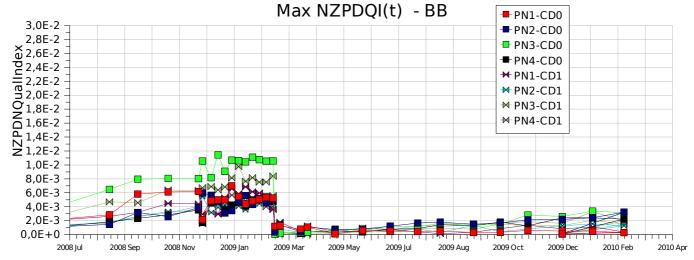


Figure 5: Max of NZPD quality index for all pixels and CCD - BB

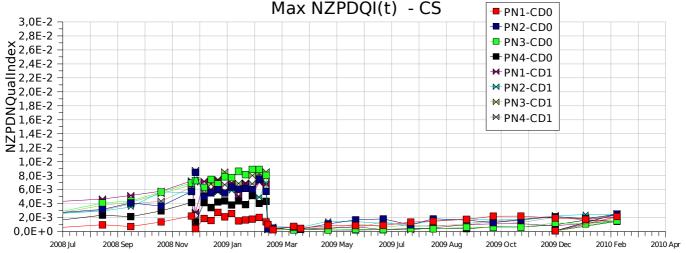


Figure 6: Max of NZPD quality index for all pixels and CCD - CS

As soon as average BZPDNZPDQualIndexBB and CS still below 0.03 on-board reduced spectra are robust to an instrument mode change.

On February 2009 we have updated the on board reduced spectra. As a consequence the NZPD quality indicator has decreased which means that the reduced spectra quality of the on-board configuration has increased.

## 4.3.3 Second level flags and quality indicators

All second level flags and indicators are stable and nominal.





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## 4.3.4 Conclusion

L0 Flag and quality indicators are stable.

## 4.4 LEVEL 1 DATA QUALITY (L1)

## 4.4.1 Overall quality

The IASI overall quality is shown as the orbit averages of the quality indicator for the individual pixels in the next figure.

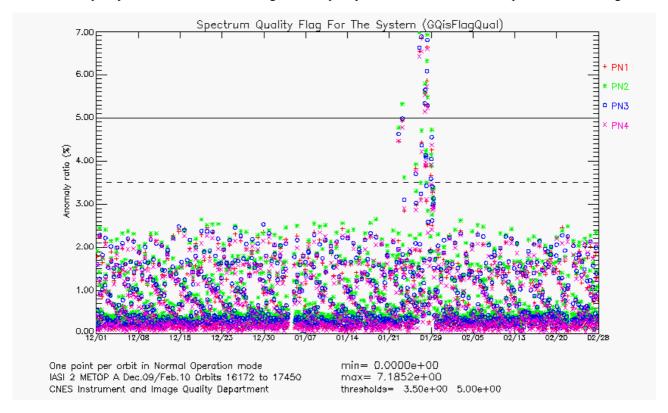


Figure 7: IASI L1 data quality orbit average

One should note that, over the period covered by the present document, the averaged data rejection ratio is less than 1%. The high GQisFlagQual on end of January corresponds to overflows.





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## 4.4.2 **Main flag and quality indicator parameters**

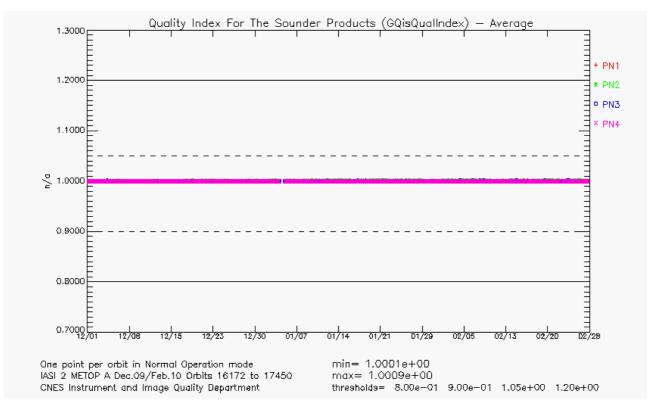


Figure 8: GQisQualIndex average (L1 data quality index for IASI sounder)

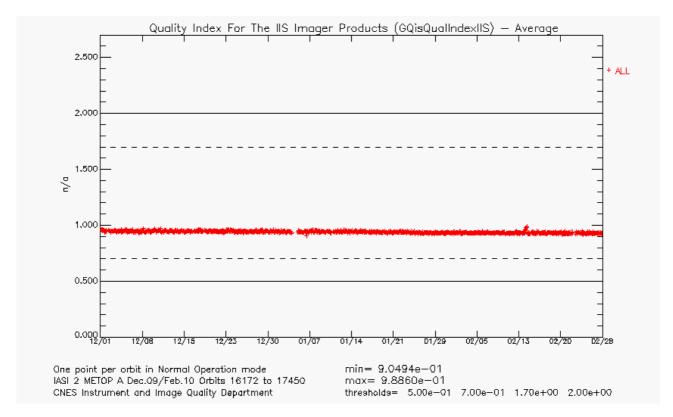


Figure 9: GQisQualIndexIIS average (L1 data quality index for IASI Integrated Imager)





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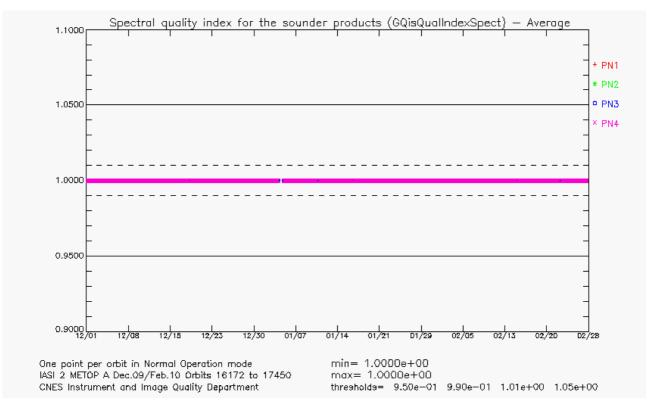


Figure 10 : GQisQualIndexSpect average (L1 data index for spectral calibration quality)

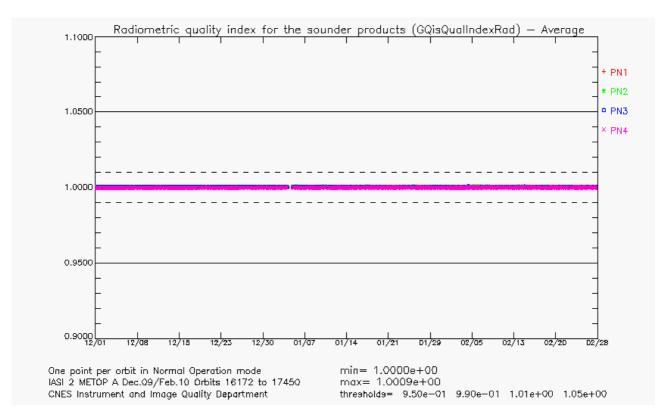


Figure 11 : GQisQualIndexRad average (L1 data index for radiometric calibration quality)





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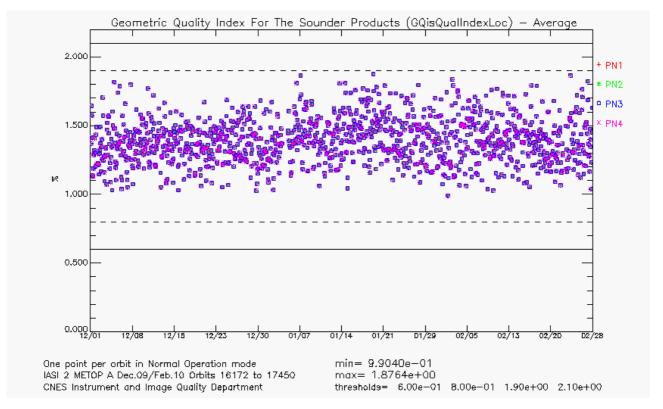


Figure 12: GQisQualIndexLoc average (L1 data index for ground localisation quality)

## 4.4.3 Second level flag and quality indicators

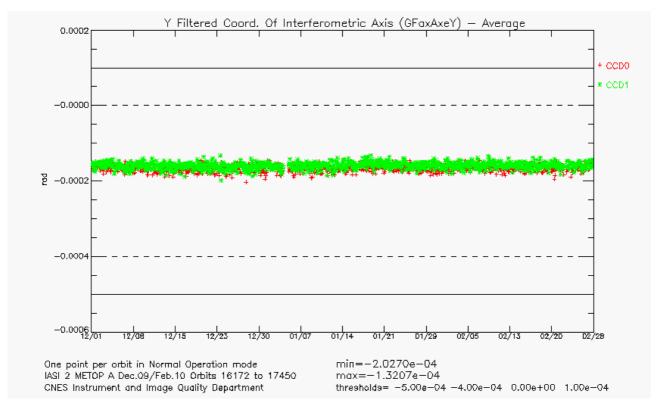


Figure 13: GFaxAxeY average (Y filtered coordinates of sounder interferometric axis)





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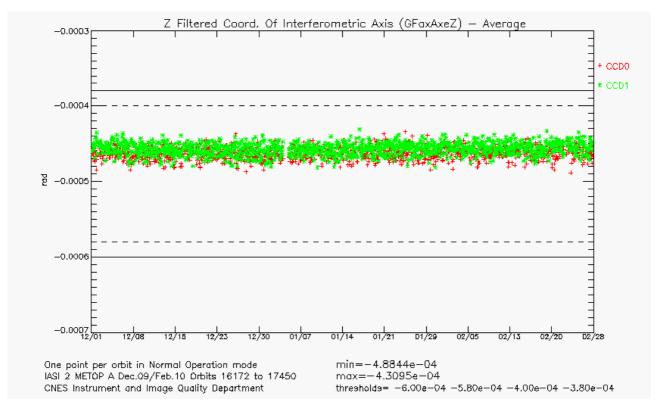


Figure 14: GFaxAxeZ average (Z filtered coordinates of sounder interferometric axis)

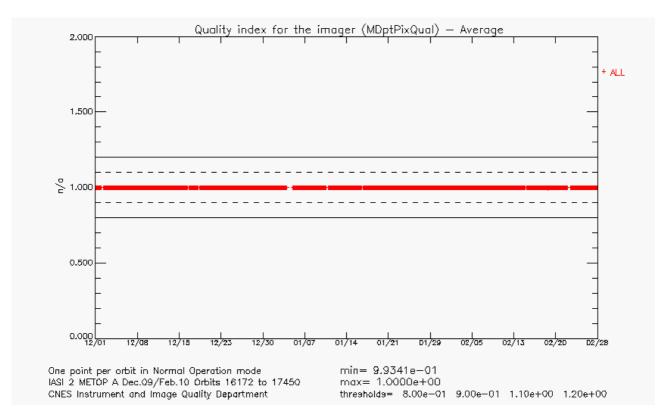


Figure 15: MDptPixQual average (L1 quality index for IASI integrated imager / fraction of not dead pixels)





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#### 4.4.4 Conclusion

L1 Flag and quality indicators are stable.

#### 4.5 SOUNDER RADIOMETRIC PERFORMANCES

#### 4.5.1 Radiometric Noise

Monitoring the radiometric noise allows to monitor the long term degradation of the instrument as well as to look for punctual anomaly of IASI or other component of METOP.

Monthly noise estimation (CE)

This monthly estimation is performed during routine External Calibration on BB views.

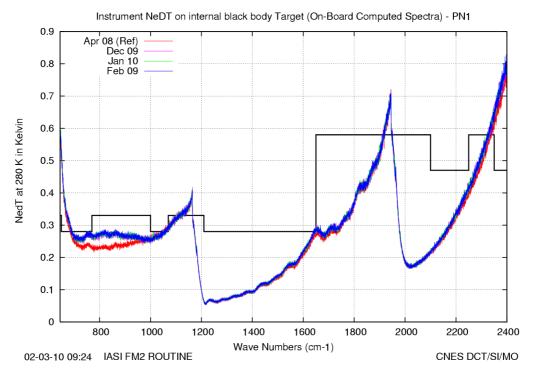


Figure 16: Instrument noise evolution between start and end of the period

The instrument noise is very stable apart from ice effect between 800 and 1000 cm<sup>-1</sup>. This point will be developed in section 4.5.3.1.

#### 4.5.2 Radiometric Calibration

The radiometric calibration allows one to convert an instrumental measurement into a physical value. As far as IASI is concerned, the radiometric calibration is used to convert an interferogram into an absolute energy flux by taking into account instrument discrepancies. Even if the calibration has been studied on ground, it has to be continuously monitored in-flight in order to follow any potential degradation of the instrument (optics, detectors ...).

<u>Approach</u>: Radiometric fine characterization has been done during ground testing and Cal/Val. All parameters likely to cause a failure in radiometric calibration process have been identified and are continuously monitored. As long as they remain stable, there is no problem with radiometric calibration.





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#### Evolution of scanning mirror reflectivity

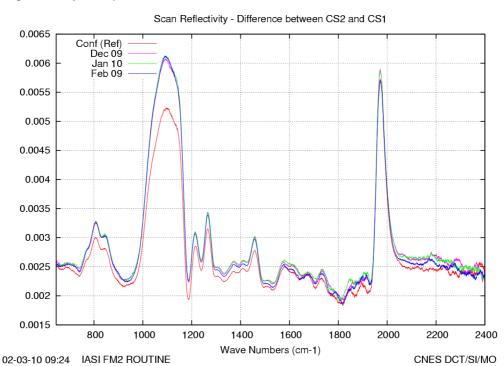


Figure 17: Scan mirror reflectivity evolution

The reference reflexivity (in red) is the same since the launch. We see a slight evolution within [1000-1100 cm<sup>-1</sup>] band. Values for wavenumbers greater than 2400 cm<sup>-1</sup> are not significant because of instrument noise.





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The next figure shows the translation of scan mirror reflectivity in terms of maximum radiometric calibration error for different scene temperatures.

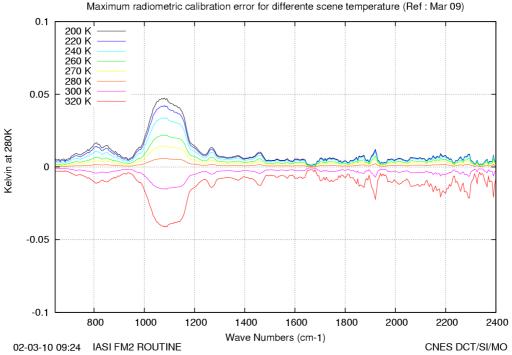
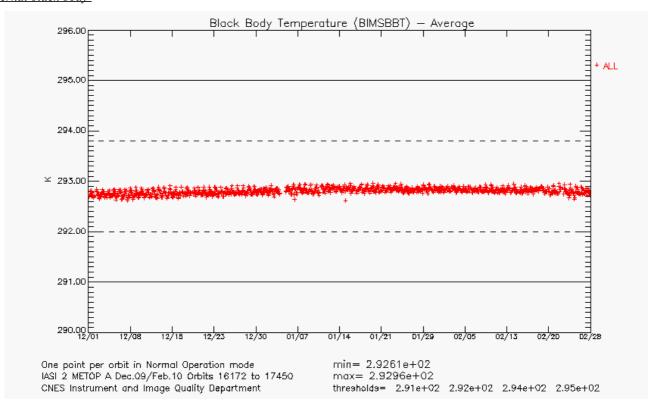


Figure 18: Radiometric calibration error due to scan mirror reflectivity dependency with viewing angle Maximum effect on SN1 for different scene temperature

In any cases radiometric calibration maximum error is lower than 0.05K. This value is twice lower than the specification (0.1K).

#### Internal black body







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Figure 19: Black Body Temperature

#### Non linearity of the detection chains

Non-linearity tables of the detection chains still nominal as long as sounder focal plane temperature variation amplitude is lower than 1K.

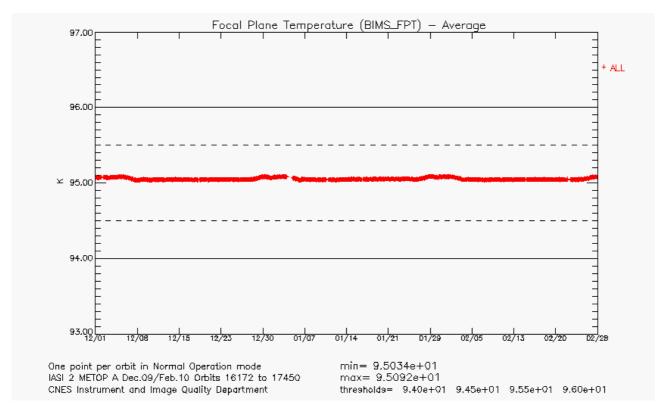


Figure 20 : Focal Plane Temperature





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## 4.5.3 Optical Transmission

#### 4.5.3.1 Ice

The IASI interferometer and optical bench are regulated at 20°C temperature, while the cold box containing cold optics and detection subsystem is at about -180°C. Water desorption from the instrument causes ice formation on the field lens at the entrance of IASI cold box. This desorption phenomenon is particularly important at the beginning of the instrument in-orbit life. That's why one of the very first activities of IASI in-orbit commissioning was an outgassing phase consisting in heating the cold box up to 300 K during 20 days. This operation allows removing most of the initial contaminants coming from IASI and other MetOp instruments. A routine outgassing is then needed from time to time to remove ice contamination, but less and less frequently as the desorption process becomes slower. A first run of this routine outgassing procedure (shorter duration and at 200 K), was done for validation purpose during commissioning phase in December 2006. The second one, which was actually the first in routine phase, was done in March 2008.

The maximum acceptable degradation of transmission is about 20% loss at 850 cm $^{-1}$  (which corresponds to an ice deposit thickness of about 0.5  $\mu$ m).

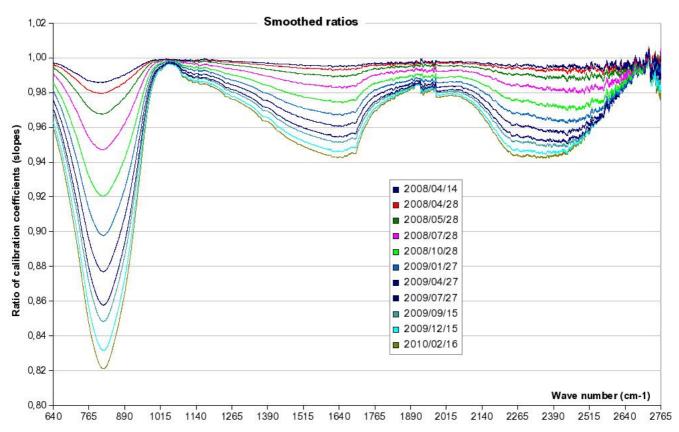


Figure 21: Ratio of calibration coefficient slopes as a function of wave number and time after the second decontamination





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#### 4.5.3.2 Prediction of decontamination date

The transmission degradation rate is regularly monitored by CNES TEC through gain measurements given by calibration coefficients ratios.

The loss of instrument gain due to ice contamination is, as expected, decreasing over time.

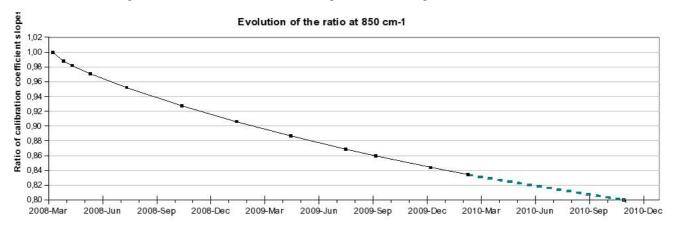


Figure 22: Temporal evolution of calibration ratio coefficient slopes since the last decontamination.

A linear extrapolation had been added to determined a rough date for the next decontamination (relative gain evolution of 0.8)

## 4.5.4 Interferometric Contrast

The interferometric contrast is defined as the interferogram fringe discrimination power. Figure 23 shows temporal evolution of instrument contrast since the beginning of IASI life in orbit for all pixels and all CCD.

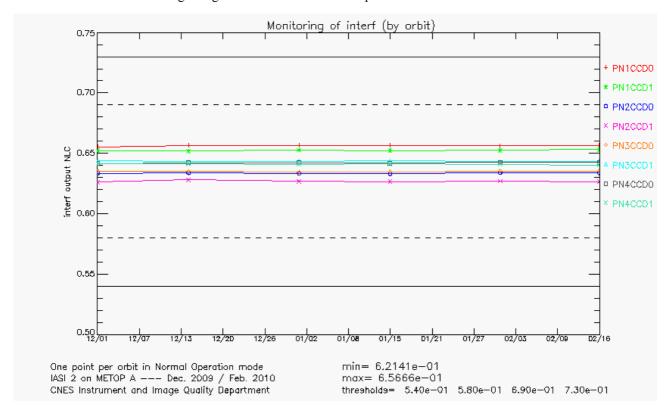


Figure 23: Monitoring of contrast for SB3





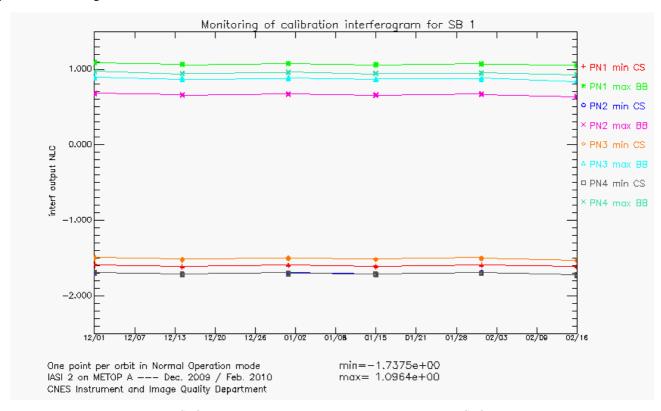
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## 4.5.5 <u>Detection Chain</u>

Detection chains are tune in gain and offset via telecommand. The goal is to avoid saturation while conserving the maximum dynamic to limit digitalization noise.



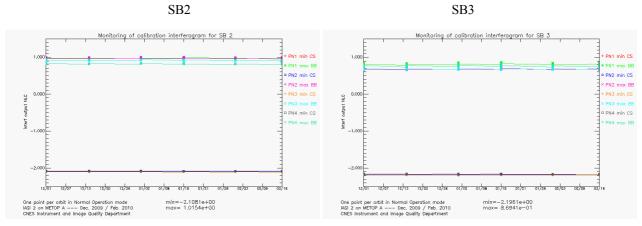


Figure 24: Monitoring of detection chain margins

Margins are sufficient for now.

## 4.5.6 Conclusion

The radiometric performances of IASI are nominal and stable. A linear extrapolation of the actual contamination ratio leads to an earliest date for the next decontamination of end of 2010.





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#### 4.6 SOUNDER SPECTRAL PERFORMANCES

This part is specific to hyperspectral sounders. The goal of the spectral calibration is to provide the best estimates of spectral position of the 8461 IASI channels.

The large sensitivity of infrared spectrum to spectral calibration errors has lead to stringent specifications:

- A priori knowledge of spectral position better than of 2.10<sup>-4</sup> (design)
- A posterior maximum spectral calibration relative error of 2.10-6 (after calibration by OPS)

In order to reach the specification of 2.10<sup>-6</sup>, we need an accurate Instrument Spectral Response Function (ISRF) model. This model have been done and validated in the early time of IASI development.

For sake of operational time constrain, complete ISRF calculation is not done in real-time by OPS software but pre-calculated and stored in a database called "spectral database". OPS processing determine on-line the most relevant instrument function to be used by OPS with respect to current values of a set of parameters (interferometric axis, cube corner offset...).

The approach to monitor IASI spectral performances is very similar to the one used for radiometric calibration. Spectral calibration fine characterization has been done during ground testing and Cal/Val. All parameters likely to cause a failure in spectral calibration process have been identified and are continuously monitored. As long as they remain stable, there is no problem with IASI spectral calibration.

## 4.6.1 <u>Dimensional Stability Monitoring</u>

#### 4.6.1.1 Monitor the position of the interferometric axis

Since the drift of the interferometer axis is lower than  $300 \mu rad$ , there is no need to update the "spectral database", see chapter 4.4.3.

#### 4.6.1.2 Cube Corner constant offset

#### **Cube Corner offset Variation** -9 -10 -11 CCM Offset in Microns -13 -14 Offset Z CD0 -15 Offset\_Z CD1 Offset\_Y CD0 -16 Y CD1 Offset -17 -18 -19 -20 -2 -22 2007/Jul 2008/Jan 2008/Jul 2008/Oct 2009/Jan 2009/Apr 2009/Jul 2009/Oct 2010/Jan 02-03-2010 IASI FM2 ROUTINE PHASE CNES DCT/ME/EI

Figure 25 : Cube Corner offset variation

Since the drift of cube corner offset is lower than 4 µm, there is no need to update the "spectral database".





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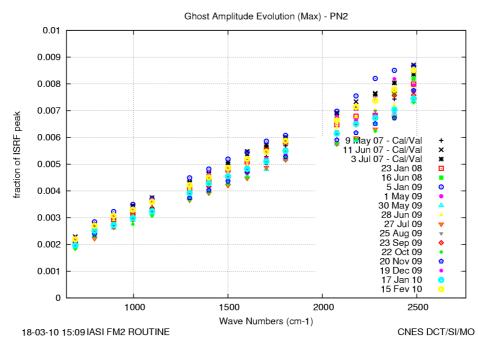
## 4.6.2 Ghost evolution monitoring

On-ground test of the instrument has shown a perturbation in the ISRF mainly caused by micro-vibrations of the interferometer separator blade. The amplitude of these micro-vibrations was characterized on ground and is measured on board.

Ghost origin is understood to be due to micro-vibrations of the beam-splitter. It is therefore stronger for the FOVs which project onto the top part of the beam-splitter (which vibrates more), and weaker for the FOVs which project onto the bottom part of the beam-splitter as this is attached to the optical bench.

The ghost affects the ISRF basically by replicating it at about  $\pm 14$ cm<sup>-1</sup>. Of course, the amplitude of these replications is very low with respect to ISRF maximum value. The amplitude and the central wave number of ISRF replications are function of: cube corner velocity, frequency and mechanical amplitude of the beam-splitter vibration and wave number.

We are continuously monitoring the impact of the ghost on ISRF by monitoring, for each wave numbers, the maximum amplitude of the replicated ISRF with respect to  $ISRF_{max}$  value using monthly external calibration (BB views). The evolution over time of ghost amplitude with respect to  $ISRF_{max}$  amplitude is shown below for pixel 2 and 4.







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Ghost Amplitude Evolution (Max) - PN4

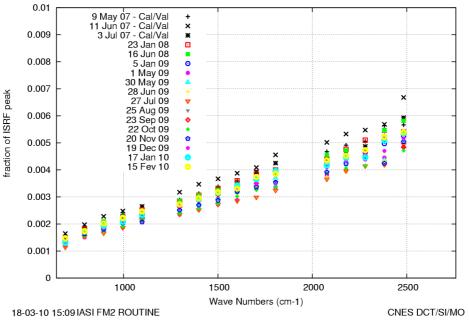


Figure 26: Optical bench Temperature (Top: pixel 2, bottom: pixel 4)

Ghost amplitude as a function of wave number for different time.

Maximum values of  $ISRF_{max}$  (@2760 cm<sup>-1</sup>) are respectively 0.9% for pixel 1-2 and 0.6% for pixel 3-4. We don't see any significant evolution over time.

Pseudo-noise induce by the ghost is very low (about 0.03K) and under control as soon as all cube corner velocity, frequency and mechanical amplitude of the beam-splitter vibration remain stable.

## 4.6.3 <u>Instrument parameters</u>

#### 4.6.3.1 Cube corner offset

see section 4.6.1.1.

#### 4.6.3.2 Cube corner velocity

Refer to REVEX, paragraph 5.5.





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#### 4.6.3.3 Interferometer optical bench temperature

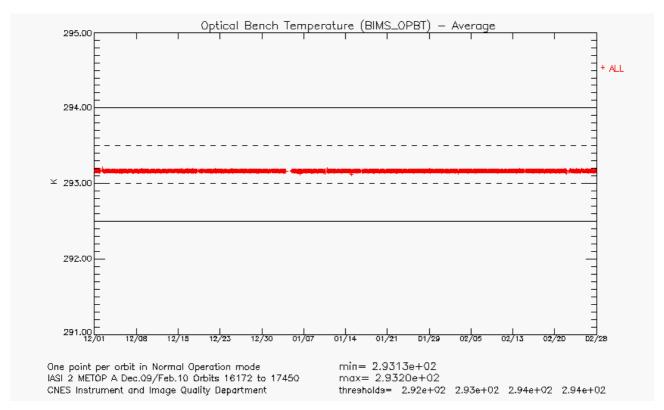


Figure 27: Optical bench Temperature

### 4.6.4 Conclusion

All parameters impacting IASI spectral calibration are stable and within specifications.

## 4.7 GEOMETRIC PERFORMANCES

The geometric calibration is performed on ground (level 1 processing). Most of the analyses of geometric performances require being in external calibration mode.

Specifications are the following: the IIS/AVHRR co-registration has to be better than 0.3 AVHRR pixel while the IIS/sounder co-registration has to be better than 0.8 mrad.

## 4.7.1 Sounder / IIS co-registration monitoring

This monitoring is performed one time a year, generally around September for REVEX.





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## 4.7.2 IIS / AVHRR co-registration

The following figures show a comparison of IIS-AVHRR offsets (GlacOffsetIISAvhrr) mean profiles.

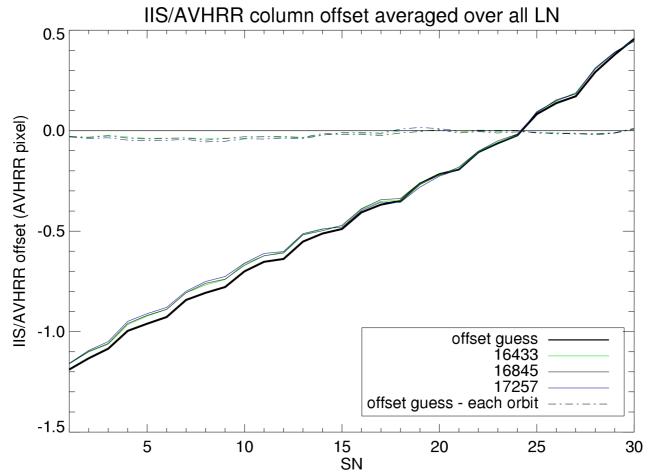


Figure 28 : Column offset (black) guess vs. column offset averaged over all lines (LN) as a function of the scan position (SP=SN), and orbit number





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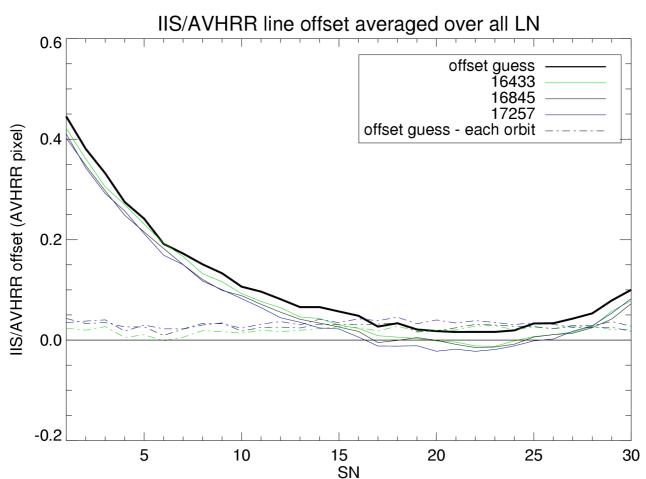


Figure 29: Line offset guess (black) vs. line offset averaged over all lines (LN) as a function of the scan position (SP=SN), and the orbit number

## 4.7.3 Conclusion

The sounder pixel positions are considered stable and well within specification

IIS-AVHRR offset is lower than two pixels and stable over time (less than 0.3 AVHRR pixels over two months), the co-registration is within the specification.





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## 4.8 IIS RADIOMETRIC PERFORMANCES

The main task of IIS is to insure a good relative positioning of IASI sounder pixels with respect to AVHRR. Its performances are studied each month using routine External Calibration data.

## 4.8.1 IIS Radiometric Noise Monitoring

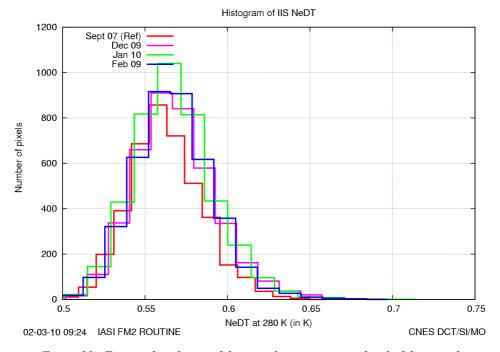


Figure 30: Temporal evolution of the noise between start and end of the period

Radiometric noise of the IIS is very stable and lower than the specification of 0.8K.





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## 4.8.2 IIS Radiometric Calibration Monitoring

In order to assess the stability of IIS radiometric calibration, we follow the time evolution of slope and offset coefficients. Figure 31 shows a comparison of slope and offset coefficients matrix between start and end of the period.

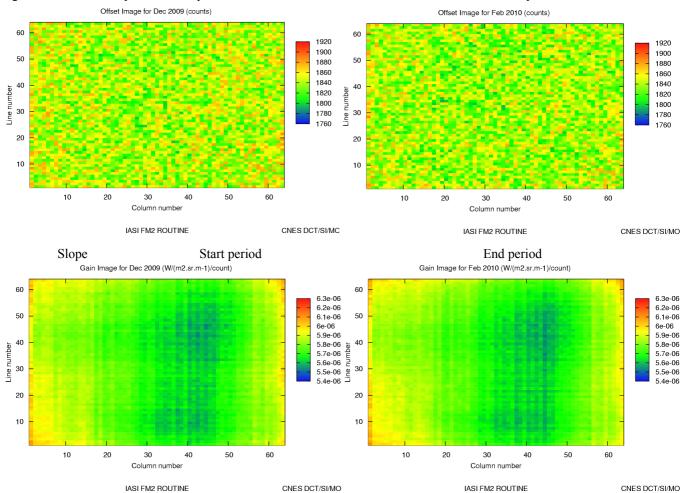


Figure 31: Slope and offset coefficients matrix





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The complete time series of average slope and offset coefficients is given in Figure 32.

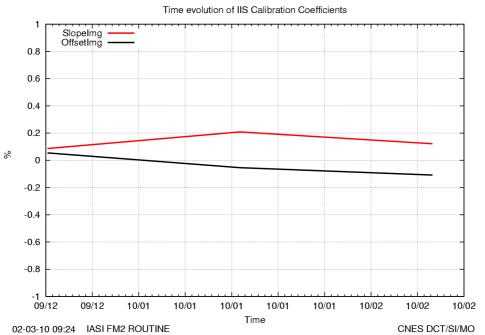


Figure 32: Evolution in % of average of slope (red curve) and offset (black curve) coefficients

The slope coefficient is stable. The offset coefficient is slightly evolving (0.4%). This evolution is likely to be linked with the slight evolution of IIS focal plan temperature.

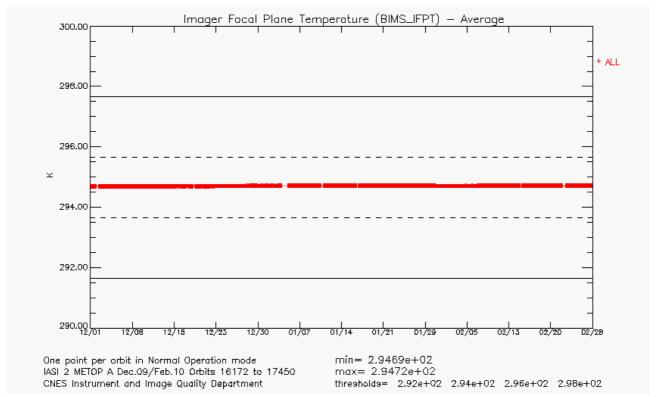


Figure 33 : IIS Focal Plane Temperature

#### 4.8.3 Conclusion

The radiometric performance of IIS is very stable and within specification.

The variation observed on the focal plane temperature has no measurable impact on the radiometric performances.





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#### 5 IASI TEC AND EUMETCAST INTERFACE EVOLUTION

For more information about the IASI news please see <a href="http://smsc.cnes.fr/IASI/index.html">http://smsc.cnes.fr/IASI/index.html</a>

#### 5.1 IASI TEC EVOLUTION

Table 19 lists the evolutions within the period.

IASI TEC software version implementation		Comments		
7.1	17 December 2009	Day2 format (analyses tools)		

Table 19: IASI TEC at CNES Toulouse

#### 5.2 EUMETCAST INTERFACES

EUMETCast dissemination is used for Near Real Time data reception at the IASI TEC at CNES, Toulouse. Each orbit, L1 ENG, L1 VER, L0, and AVHRR 1B products, are received under continuous series of 3 minutes granules, which are reconstructed directly by the terminal. The EUMETCast terminal is directly connected to the TEC.

As this terminal regularly fails, a back up station was implemented by EUMETSAT to support the problem by keeping products inside the machine for a longer period than on the nominal terminal: this allows CNES to loose not too much time and to retrieve manually the stored products if necessary.

The EUMETCAST maintenance team regularly receives logs from the nominal terminal and anomaly reports in case of crash.

The nominal EUMETCast hung up:

On Wednesday 02/12/2009 03:30 (restarted at 9:30Z --> 6h of missing products)
 On Wednesday 06/01/2010 12:07 (restarted in the following hours --> 2h48 of missing products)
 On Sunday 10/01/2010 22:56 (restarted on Monday 11<sup>th</sup> --> 8h20 of missing products)
 On Friday 15/01/2010 15:45 (restarted in the following hours --> 1h24 of missing products)
 On Wednesday 03/02/2010 12:53 (restarted in the following hours --> 1h09 of missing products)
 On Monday 22/02/2010 19:41 (restarted on Tuesday 23<sup>th</sup> --> 11h15 of missing products)

As these periods were not critical, products were not retrieved from the backup terminal.

Configuration of the backup terminal was modified on February 17<sup>th</sup>: the DVB card was removed and the "pentaval" service stopped. Hereunder is a figure showing the frequency of terminals failures.

#### **EUMETCast interruptions**

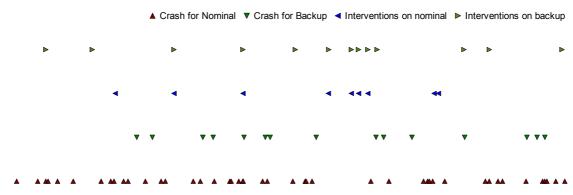


Figure 34: status of TEC's EUMETCAST terminals





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## 6 CONCLUSION AND OPERATIONS FORESEEN

#### 6.1 SUMMARY

The IASI FM2 instrument is fully operational.

The instrument configuration is the nominal one.

## 6.2 SHORT-TERM EVENTS

Moon on 03/04 January 2010

So called "day-2 evolutions" of IASI L1 PPF and consecutively IASI TEC.

#### 6.3 OPERATIONS FORESEEN

- Update of OPS configuration in order to take into account day-2 evolutions.
- Next decontamination should happen summer 2010.