

A physically based observation error covariance matrix for IASI

Hyoung-Wook Chun¹, Reima Eresmaa², Anthony P. McNally², Niels Bormann², and Marco Marticardi²

¹Korea Institute of Atmospheric Prediction Systems (KIAPS), Seoul Korea (hwchun@kiaps.org)

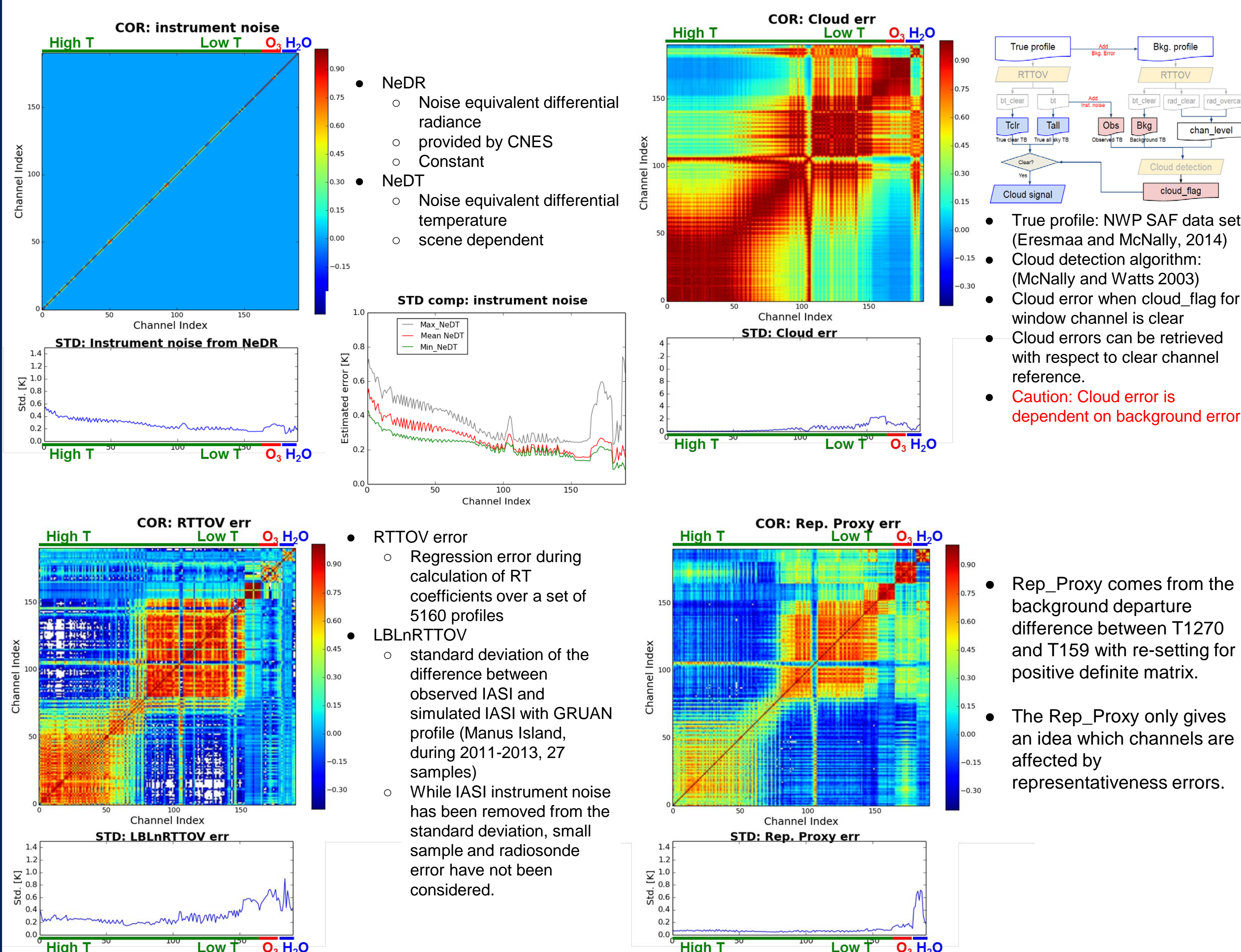
²European Centre for Medium-Range Weather Forecasts (ECMWF), Reading, UK

Introduction

Since IASI data was first assimilated operational centres have adopted a pragmatic approach and used greatly simplified representations of the error covariance matrix (e.g., Collard and McNally 2009). Inter-channel correlations have been ignored and error values inflated in parts of the spectrum where this approximation is thought to be least valid (e.g. window and water vapour channels). Even with this degree of simplification the assimilation of IASI observations has had a well documented positive impact on NWP forecasting systems (Collard and McNally 2009, Hilton et al. 2009, Guidard et al. 2011). However, more recent work using techniques to estimate the full error covariance from a diagnosis of innovation statistics have suggested that further improvements can be obtained and in particular highlighted the importance of explicitly accounting for inter-channel correlation (Weston et al. 2014, Bormann et al. 2015).

Inspired by (and indeed guided by) these encouraging results, the work described in this study explores an alternative approach to construct a full error covariance for IASI by modelling the individual sources of uncertainty and then combining these in a total error estimate. The motivation to pursue this *physical* approach (as opposed to the statistical innovation diagnosis) is threefold. Firstly, it may allow us to attribute some of the important features present in the diagnosed covariance estimates to real physical sources of error (e.g. residual cloud contamination) and may additionally provide some insight as to why the diagnosed estimates invariably need to be empirically inflated before use. Secondly, the use of a physically based (independent) derivation of the observation error covariance would reduce the potential for dependencies between background errors and observation errors in the assimilation system. Finally, if the individual sources of error (and their variability location to location) are better understood, the problem of allowing for scene dependence of observation error covariance in the assimilation scheme is significantly more tractable.

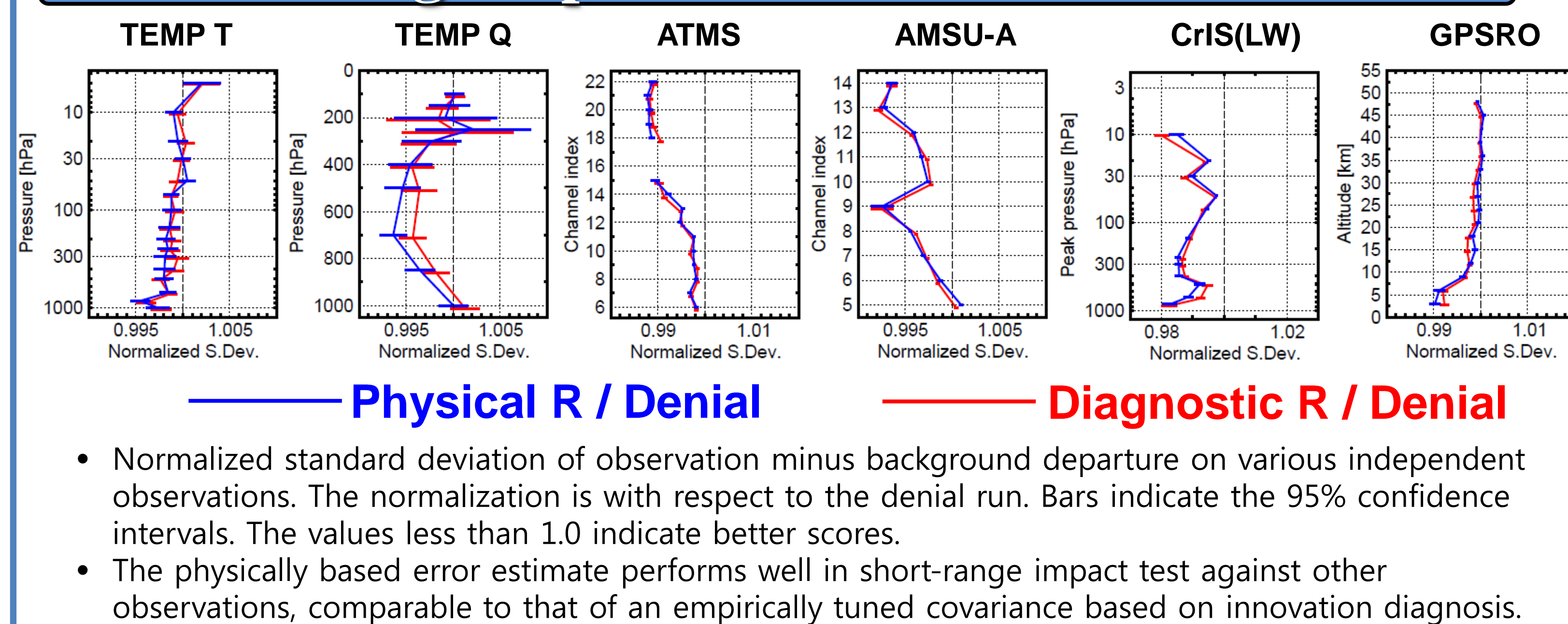
Physically based observation error (R)



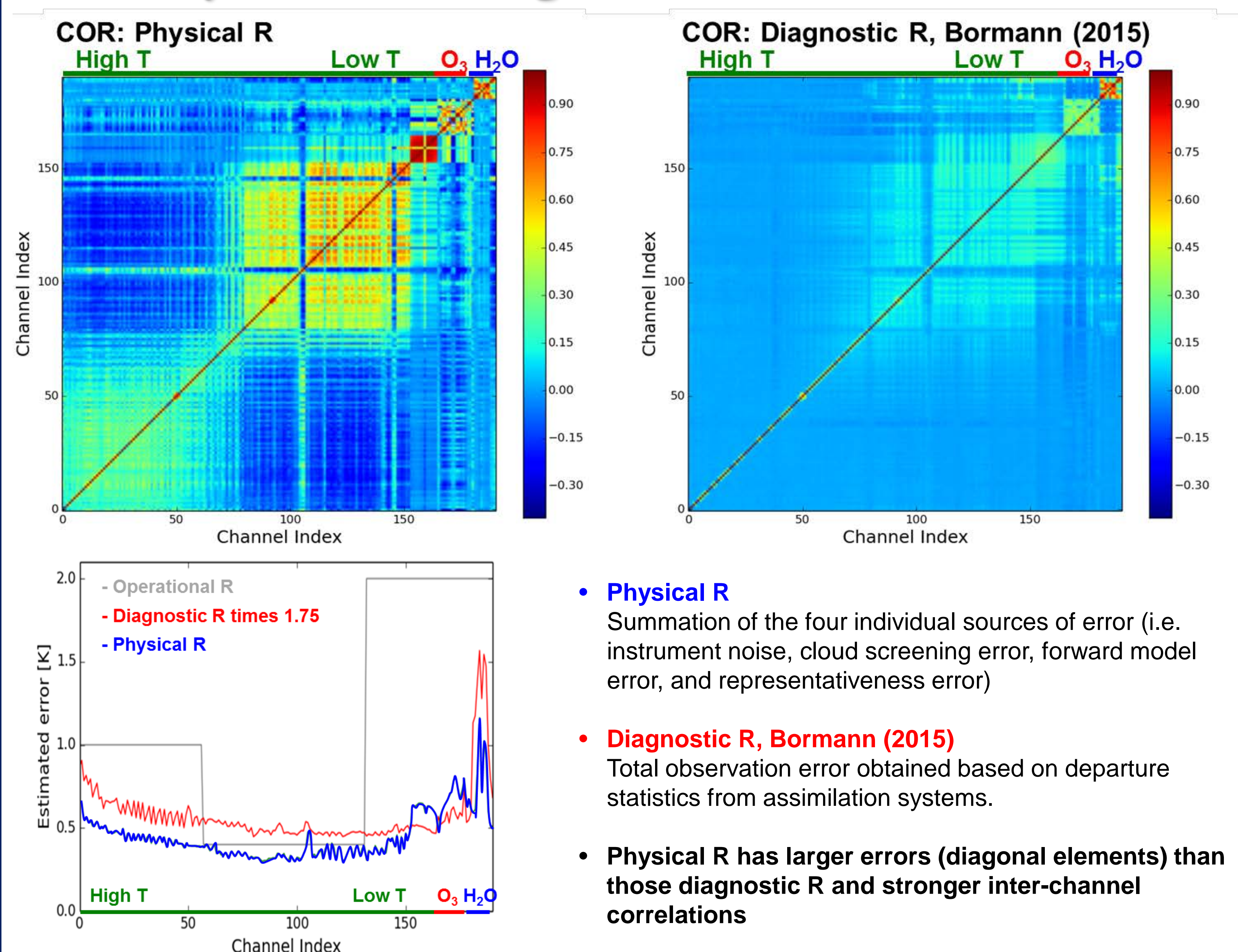
Experiments

- 191 IASI radiances are assimilated for ECMWF IFS system : CY41, T639, 137 vertical levels during 12 months (1 Jul 2014 -30 Jun 2015)
- with different kinds of IASI observation error covariance (R)
 - Control: Operational R (without inter-channel correlation) in IFS
 - Diagnostic R in Bormann et al. 2015
 - Physical R in this study
 - Denial IASI radiances

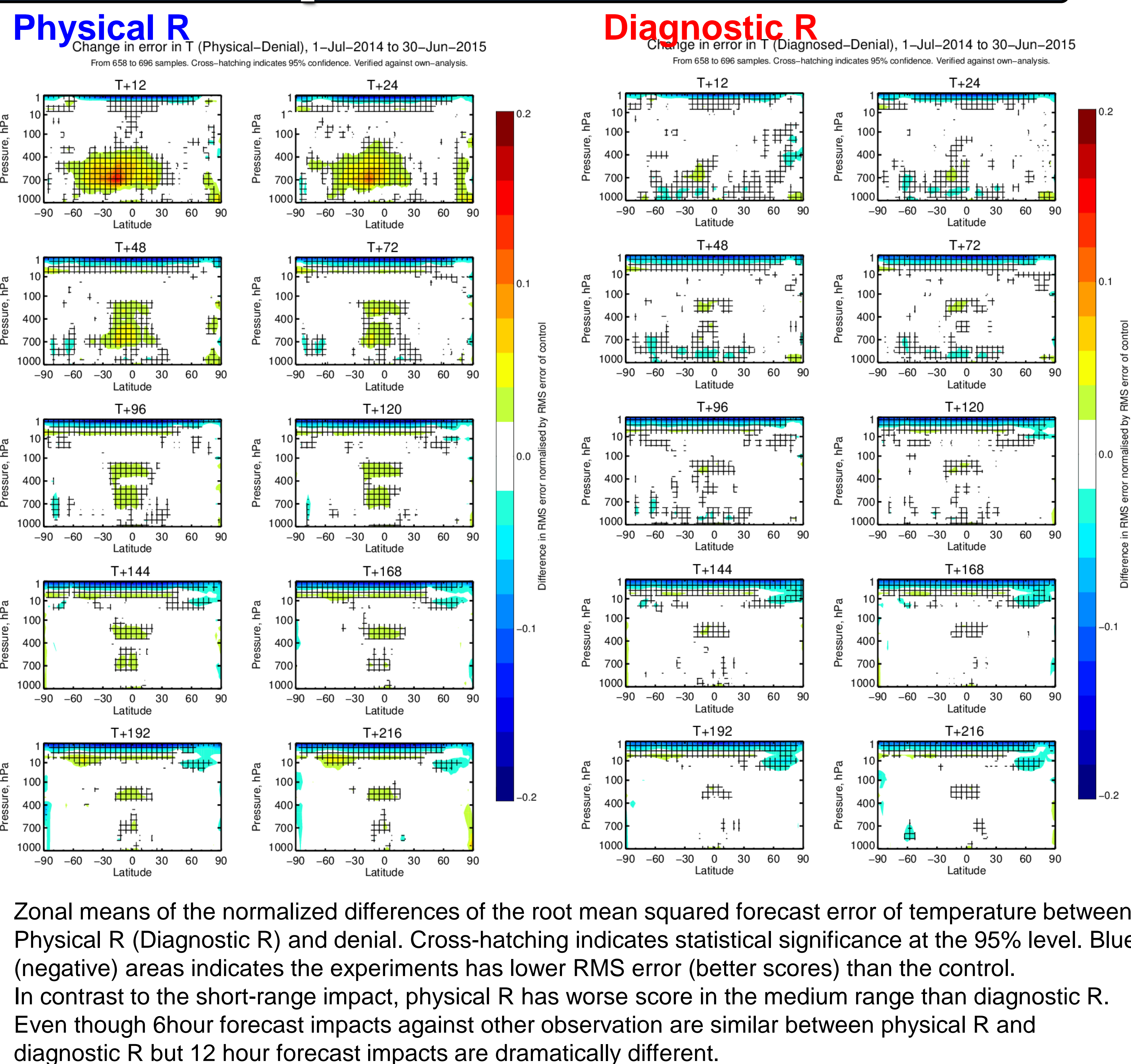
Short-range impact versus other observations



Physical R vs. Diagnostic R



Forecast impact



Summary

- Building up a physically-based observation error covariance matrix for IASI radiance assimilation from a knowledge of individual sources of error.

source	dominant channels
instrument noise	All, especially T sounding ch.
cloud error	Window ch.
radiative transfer error	All, especially O ₃ and WV ch.
representativeness error	WV ch.

- The combination of these produces a covariance with stronger inter-channel correlations than those diagnosed from innovations.
- The physically based error estimate performs well in short range impact against other observation, comparable to that of an empirically tuned covariance based on innovation diagnosis.
- In contrast to the short range, diagnostic R has better score than denial but physical R has worse score than denial in medium range forecasting.